

CWSF 2006 - Saguenay, Québec



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Line Following Robot

Division: Health Sciences

Category: Intermediate

Region: Regina

City: Regina, SK

School: Thom Collegiate

Abstract: This project investigated the ability of line following robot to follow lines on a contrasting surface. Construction of the robot had to be completed before the experiment was conducted. Two equal length courses were designed for the experiment, one a straight line, the other a circular course. The robot was able to successfully follow both of the courses for all trials.